

Investigation traction system development for lunar mobility – Part 2 la suite...

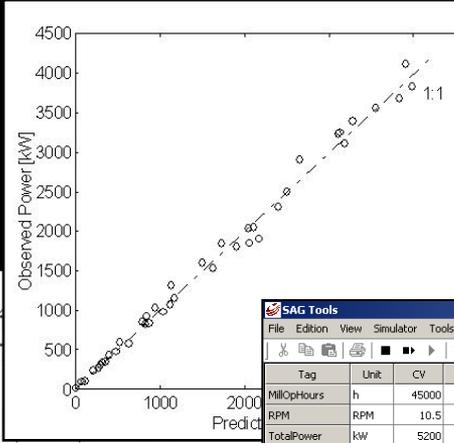


Peter Radziszewski¹, Brad Jones²

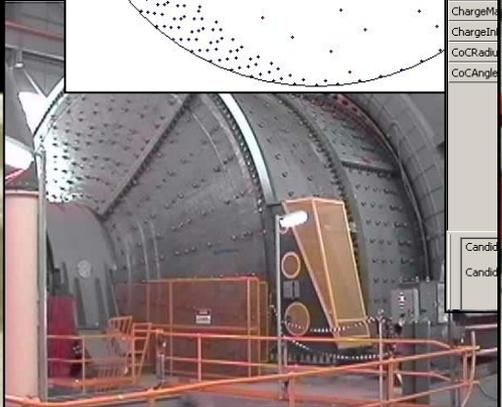
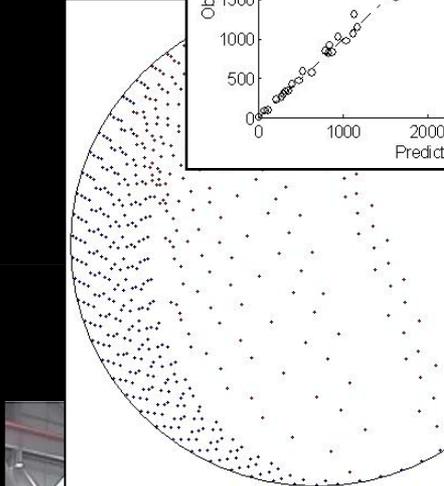
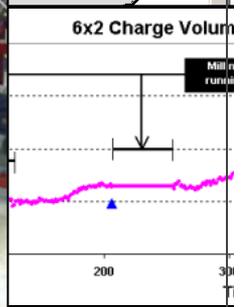
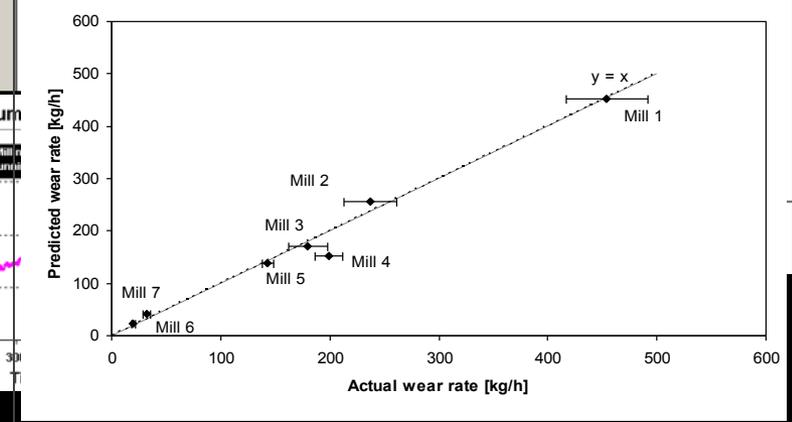
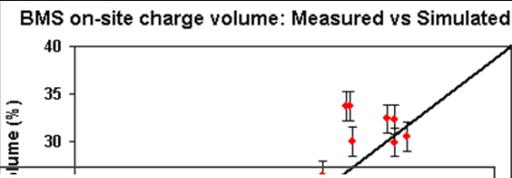
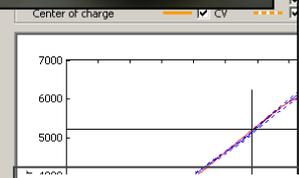
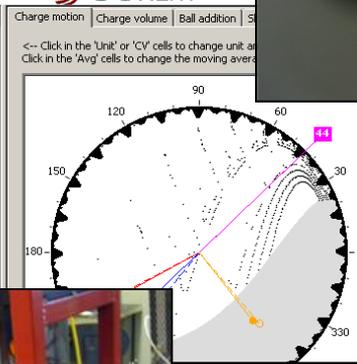
¹Mechanical Engineering, McGill University

²Neptec Design Group

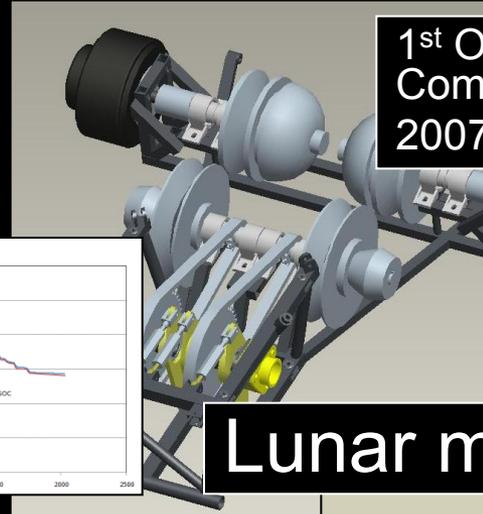
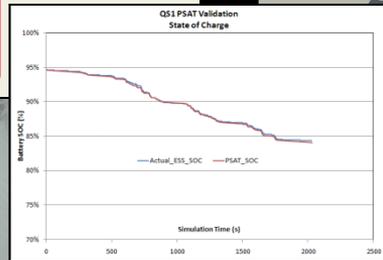
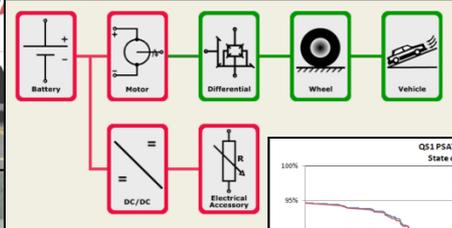
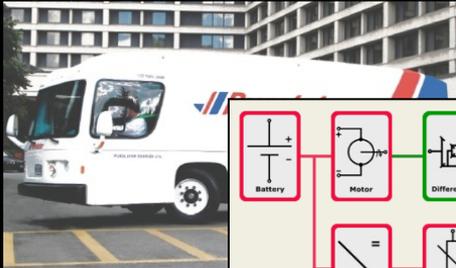
Rock



Tag	Unit	CV	Avg
MillOpHours	h	45000	45000
RPM	RPM	10.5	10.5
TotalPower	kW	5200	4606
OreDensity	kg/m ³	4199	4199
SolidFraction	%	80.0	80.0
ChargeVolume	%	29.1	24.8
SteelVolume	%	4.2	4.2
LinerWear	%	0.0	0.0
ShoulderAngle	deg	44	44
ToeAngle	deg	224	231
OuterMostAngle	deg	209	208
OreMass	t	161	132
SlurryMass	t	76.5	64.6



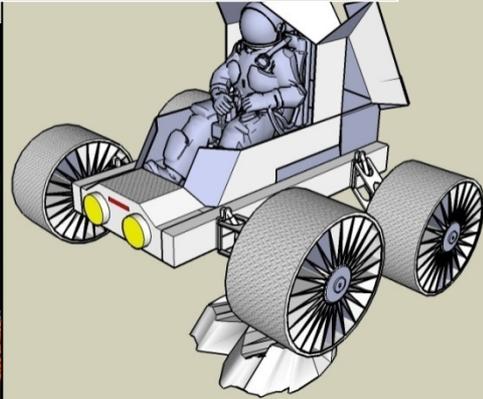
Roll



1st Overall – Hybrid Formula Competition 2007, 2008



Lunar mobility



- 1st Overall – Clean Snowmobile Challenge, Zero – emission category
- Best Design 2007
- Carried Olympic Flame Whistler 2010



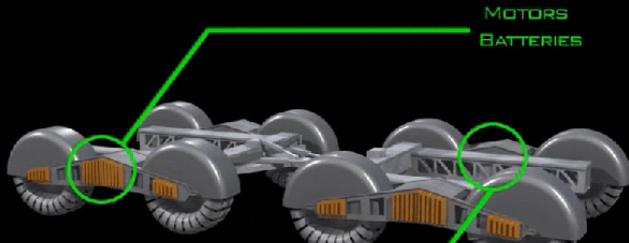
Electric motor dyno



Introduction

JUNO – from concept to multi-purpose work horse (Neptec Rover Team)

PROPULSION SYSTEM



WALKING BEAM



McGill



**NSERC
CRSNG**

Introduction

PSP/CRD project

“INVESTIGATING TRACTION SYSTEMS FOR LUNAR ROVER MOBILITY”

Goal: Define, develop and validate a compliant wheel design methodology which will be used to evaluate and compare the feasibility of different wheel configurations, steering and suspension strategies, and traction designs.



McGill



**NSERC
CRSNG**

Introduction

- Overview of wheel prototyping,
- Overview of iRings wheel prototyping,
- Avenues for further improvement,
- Summary



Overview of wheel prototyping

- Based on the literature
- Segmented type 1
- Segmented type 2
- Segmented type 3
- Brushed



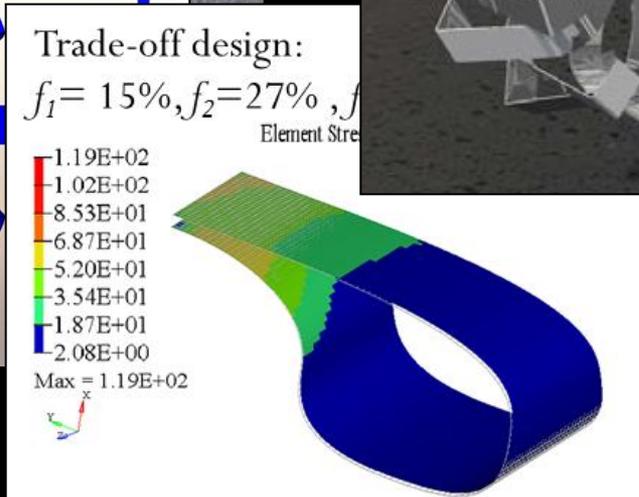
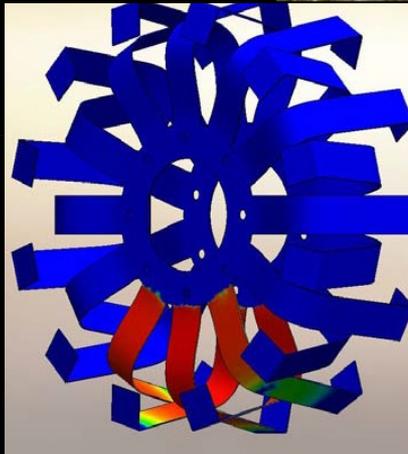
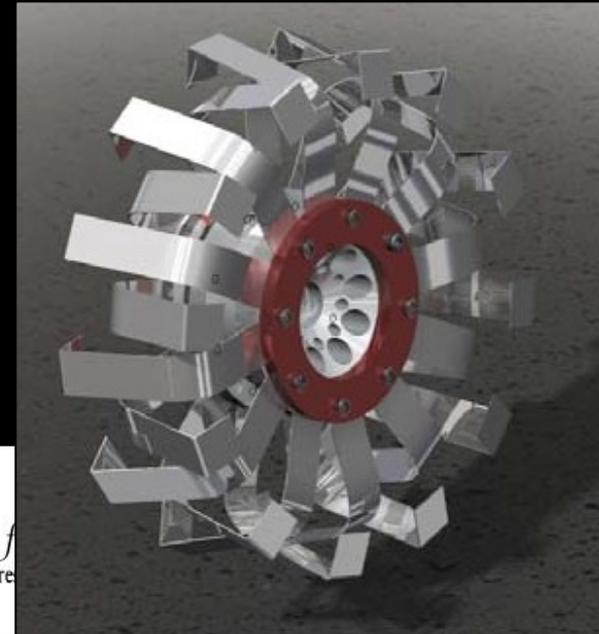
McGill



**NSERC
CRSNG**

Overview of wheel prototyping

- Based on the literature
- **Segmented type 1**
- Segmented type 2
- Segmented type 3
- Brushed



McGill

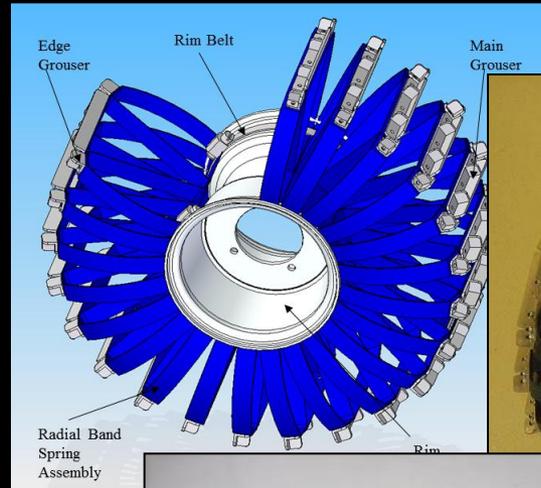


NSERC
CRSNG

Overview of wheel prototyping

Canadian Space Agency wheel design (Mo Farhat)

- Based on the literature
- Segmented type 1
- **Segmented type 2**
- Segmented type 3
- Brushed



McGill

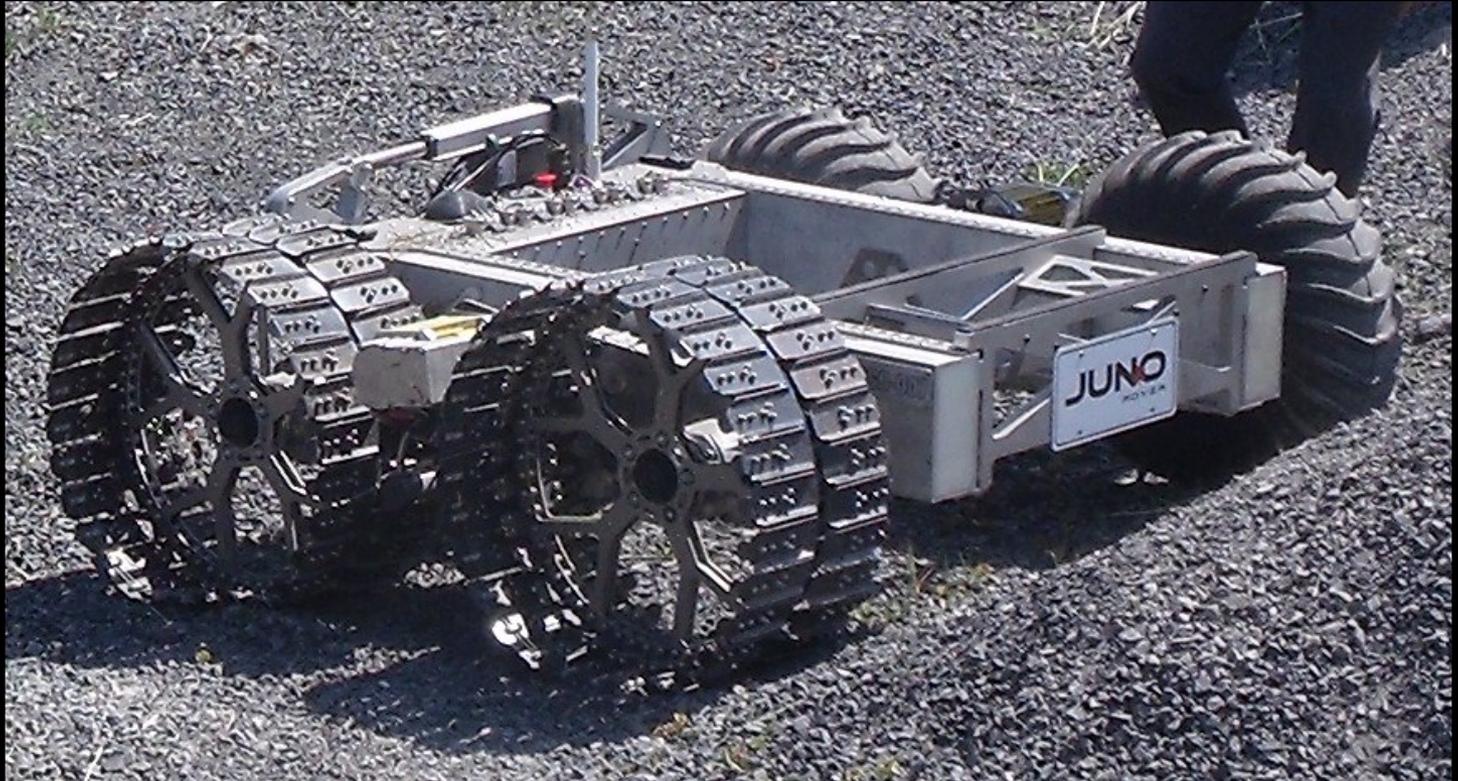


NSERC
CRSNG

Overview of wheel prototyping

Ontario Drive and Gear wheel design (Peter Visscher)

- Based on the literature
- Segmented type 1
- Segmented type 2
- **Segmented type 3**
- Brushed



McGill



**NSERC
CRSNG**

Overview of wheel prototyping

- Based on the literature
- Segmented type 1
- Segmented type 2
- Segmented type 3
- **Brushed**



McGill

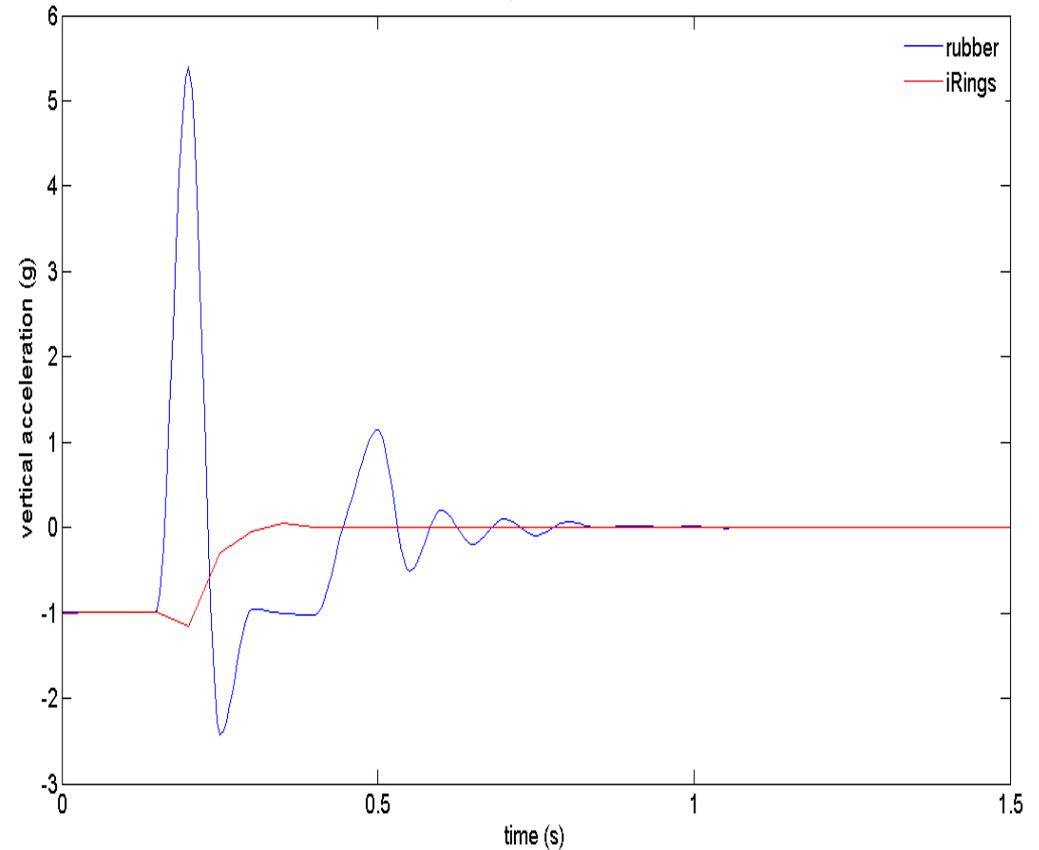


**NSERC
CRSNG**

Overview of iRings wheel prototyping



drop test - 8 inch iRings and rubber wheel,
sand, 24 inch fall

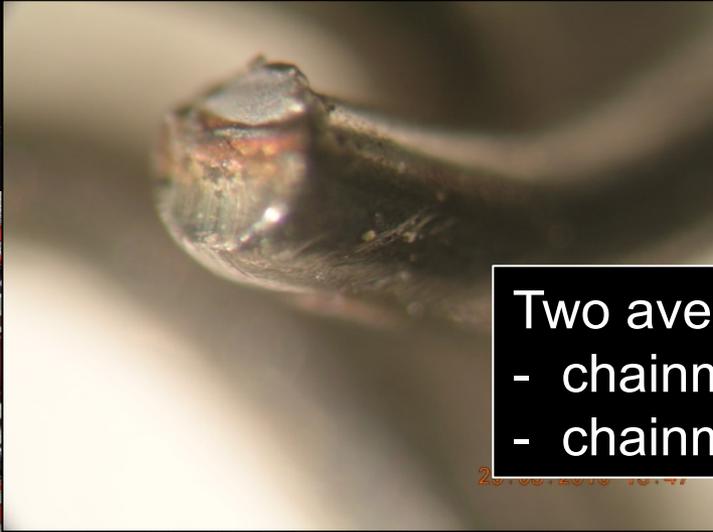
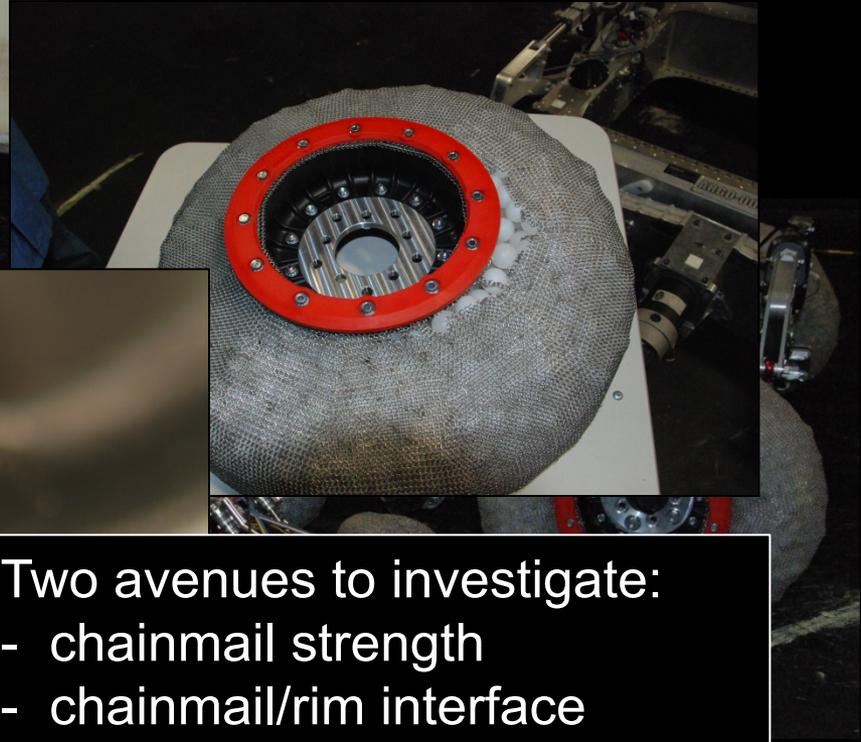


McGill



NSERC
CRSNG

Overview of iRings wheel prototyping



Two avenues to investigate:

- chainmail strength
- chainmail/rim interface



Beadlock rim



McGill



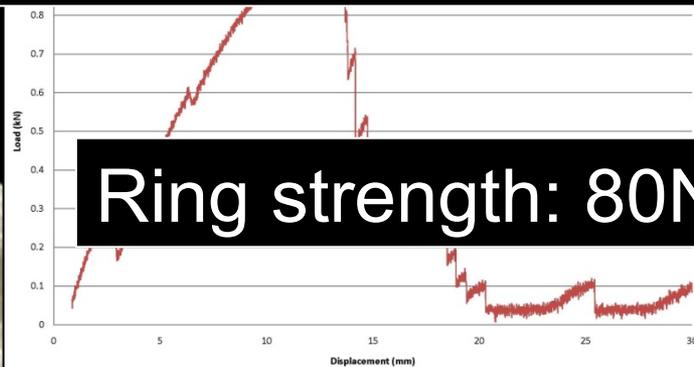
**NSERC
CRSNG**

Overview of iRings wheel prototyping

Load limits	Load Limit	Applied Load	Comment
-------------	------------	--------------	---------

Subsequent testing indicated a lot of variation (50%) in ring strength as low as 40N per ring.

→ Found a new chainmail supplier producing chainmail with ring strength (similar diameter) @ 400N.



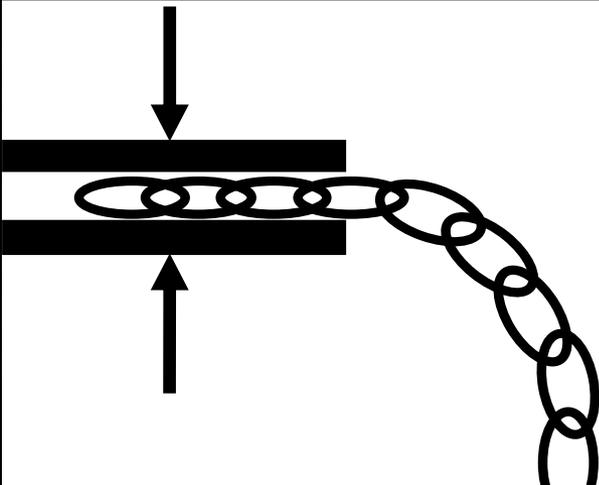
Two avenues to investigate:

- **chainmail strength**
- chainmail/rim interface



Overview of iRings wheel prototyping

Load limits	Load Limit	Applied Load	Comment
Static load criterion	8.7kN	0.47kN (190 kg/420lbs on 4 wheels)	No failure Safety factor: 18
Traction		0.35kN	No failure Safety factor: 12.3
Lateral criterion		0.59kN	No failure Safety factor: 7.3
Fatigue Sut $k_a = 0.86$ $k_b = 1$ $k_c = 0.85$		MPa alternating	No failure Safety factor: Mod. Goodman: 2.3 Gerber: 2.7 ASME Elliptic: 2.8 Langer 1 st cycle yield: 6.3

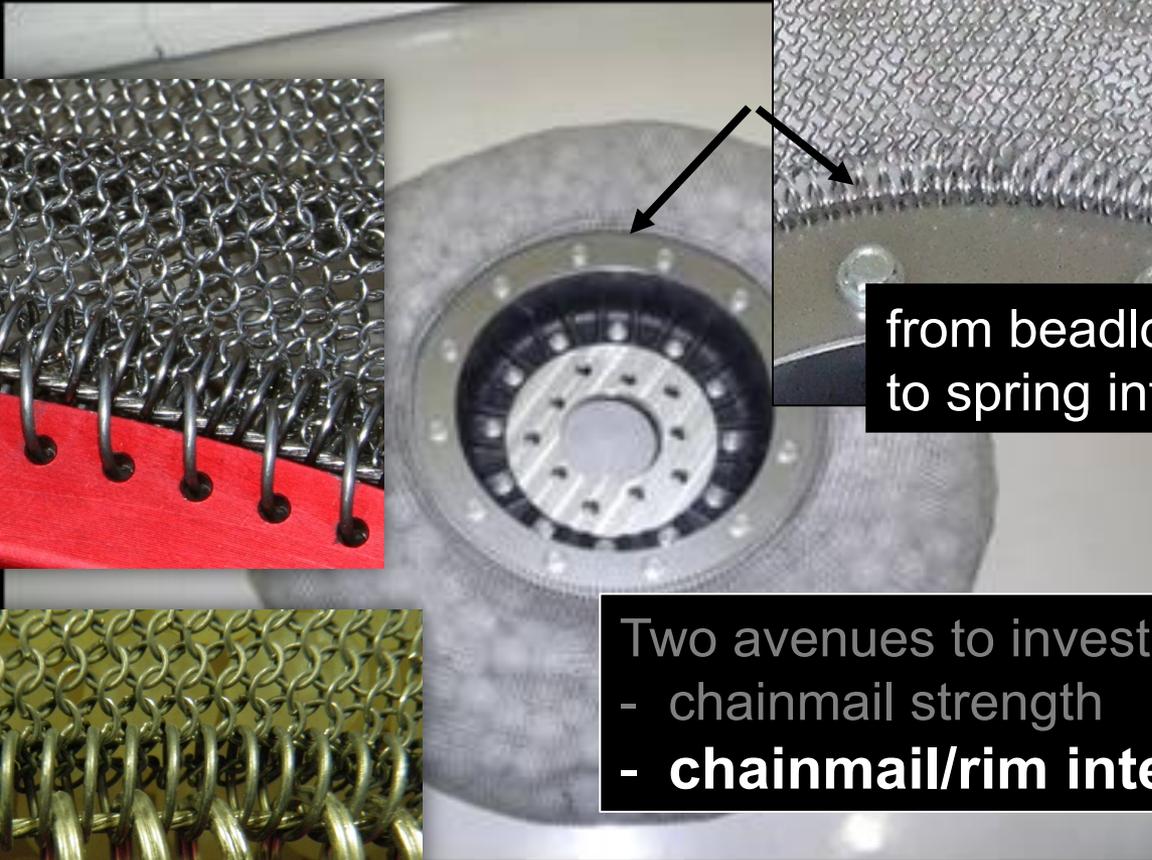


Beadlock interface locks the chainmail in a vice limiting its movement in the first number of ring rows.

Two avenues to investigate:

- chainmail strength
- **chainmail/rim interface**

Overview of iRings wheel prototyping



from beadlock interface
to spring interface.

Two avenues to investigate:
- chainmail strength
- **chainmail/rim interface**

Overview of iRings wheel prototyping

from prototype to production wheels
(JUNO Upgrade project)

Challenge:

*design a wheel using the iRings
concept that can provide failure free
travel for a minimum of 10km.*

→ maximize safety factors while
maintaining general characteristics



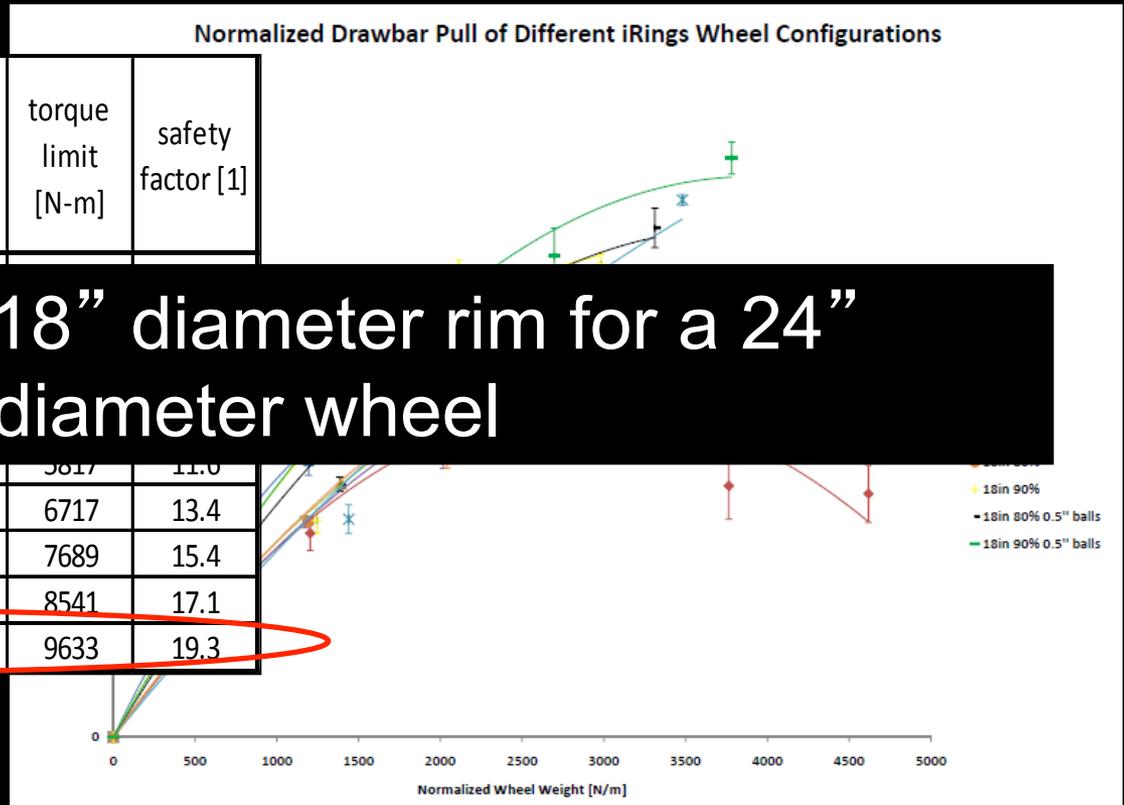
Overview of iRings wheel prototyping

from prototype to production wheels
(JUNO Upgrade project)

rim radius r [m]	rim traction force F_r [N]	rim arc length [m]	n_{rings} [1]	rim resistance F_{resist} [N]	torque limit [N-m]	safety factor [1]
0.127	2008	109.1492	27			
0.14	1821	120.3220	30			
0.152	1678	130.6353	33			
0.165	1545	141.8081	35			
0.178	1433	152.9808	38	32060	3617	11.0
0.1905	1339	163.7239	41	35260	6717	13.4
0.2032	1255	174.6388	44	37840	7689	15.4
0.2159	1181	185.5537	46	39560	8541	17.1
0.2286	1115	196.4686	49	42140	9633	19.3

→ 18" diameter rim for a 24" diameter wheel

Normalized Drawbar Pull of Different iRings Wheel Configurations



McGill

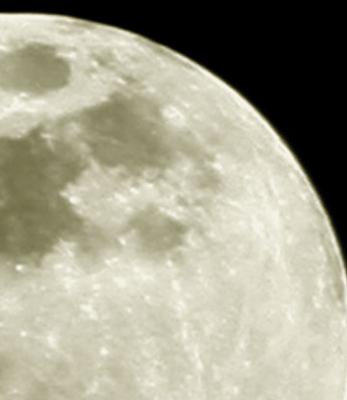


NSERC
CRSNG

Overview of iRings wheel prototyping

from prototype to production wheels

Looked to see if 10km travel would break any thing...



McGill



**NSERC
CRSNG**

Overview of iRings wheel prototyping

from prototype to production wheels

After completing a first 10km of failure free travel we had some fun.



McGill



**NSERC
CRSNG**

Overview of iRings wheel prototyping

from prototype to production wheels



After having some (failure free) fun we continued on to achieve 100km to 200km failure free travel (with some heavy weight loads)!

- over 100,000 cycles



McGill



Overview of iRings wheel prototyping

from prototype to production wheels

and then we delivered them...



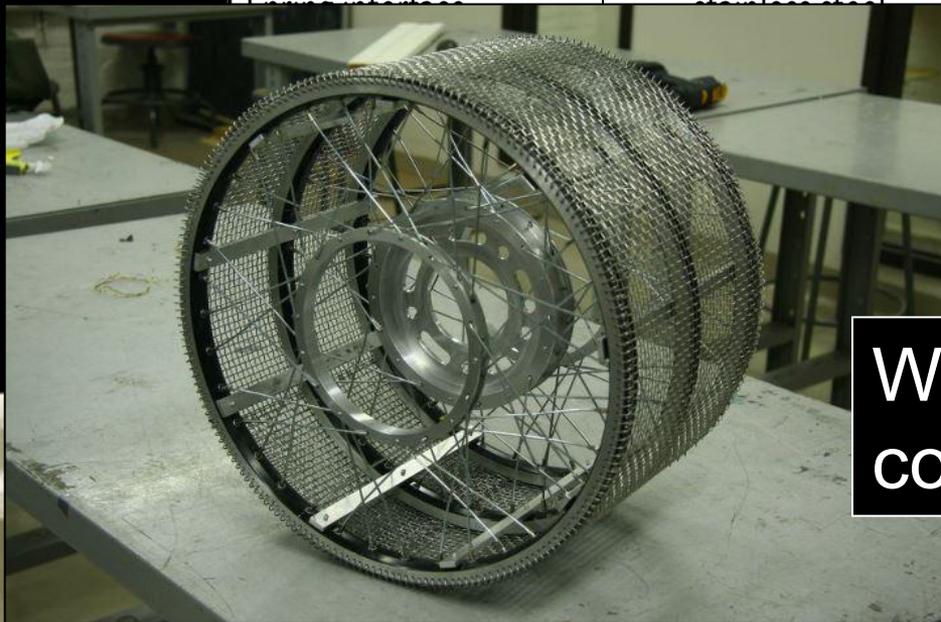
McGill



**NSERC
CRSNG**

Avenues for further improvement

	Solid propylene balls
Mass of particulate [kg]	18.2
Rim design	current design
Rim mass [kg]	5
Crane interface	stainless steel



What about elastically compliant rims?



McGill

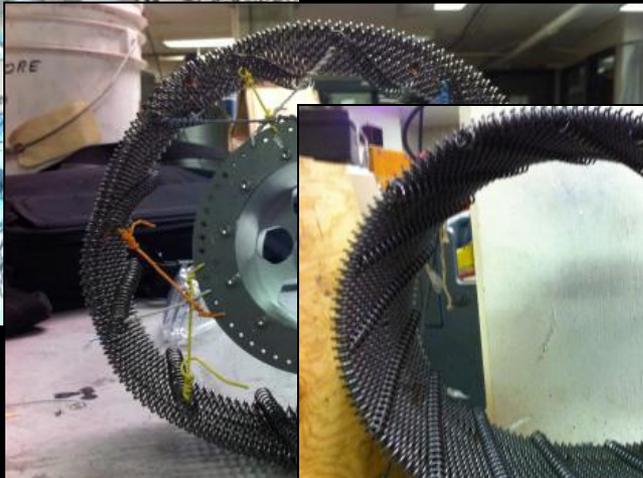
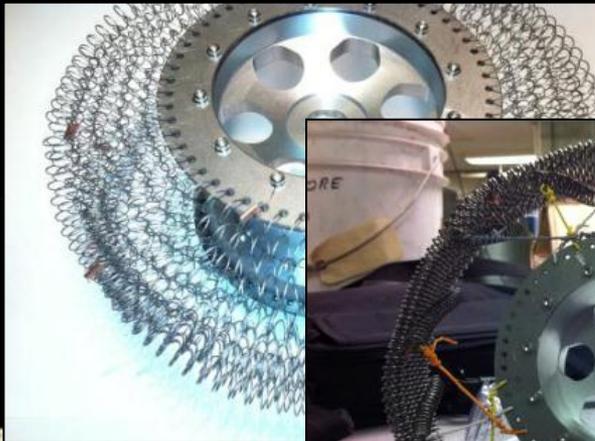
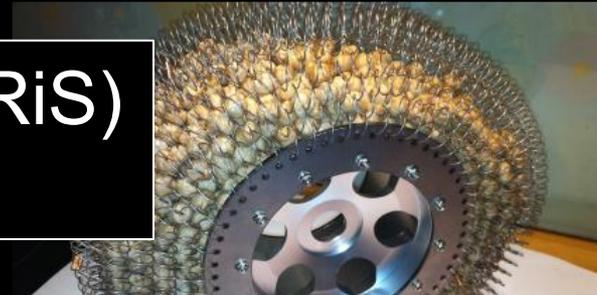


**NSERC
CRSNG**

Avenues for further improvement

Iron rings and springs (iRiS)

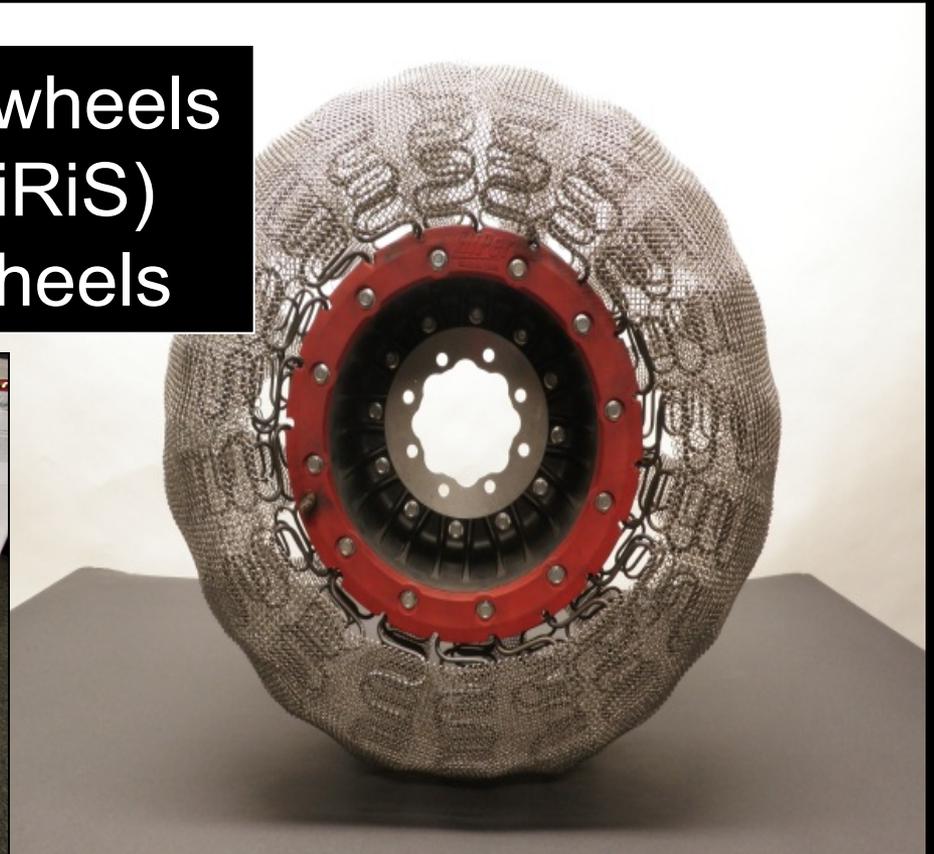
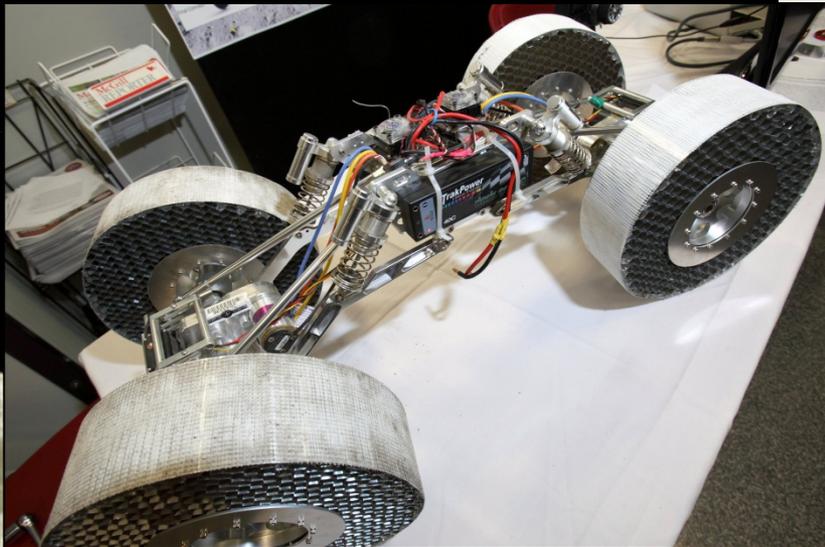
- compliant rims



Avenues for further improvement

Elastically compliant rims/wheels

- Iron rings and springs (iRiS)
- Cellular structure rim/wheels



McGill



**NSERC
CRSNG**

Summary

PSP/CRD	Variations	Number of wheels
5" diameter	9 (2 iRings, 5 segmented, 2 honey comb)	14
8" diameter	5 (iRings, 1 scaled, 2 spring, 1 honeycomb)	20
22"/24" diameter	9 (3 metal, 2 iRings, 1 spring, 1 brushed)	12
Spoked	2	2
JUNO Upgrade	6 (3 exp., 2 eng., 1 production)	15
CSA	2	8
ODG	1	8
TOTAL	33	79 (McGill 63)

- iRings is a wheel system that provides excellent traction, shock absorption, rock conforming characteristics;
- All iRings wheel components are candidates for in-situ replication:
 - particulates: centrifugal sieving, by-product of oxygen production or 3D printing
 - chainmail: 3D printing
 - rim: 3D printing
 - interface spring: 3D printing
- Compliant rim (& wheel) designs provide the possibility to engineer an iRing wheeled system with specific dampening and elastic characteristics.



McGill



**NSERC
CRSNG**

Acknowledgements

The authors would like to thank Neptec and CSA as well as NSERC CRD program for the financial support of this project.

The authors would also like to thank some 93 (20: 2008-09; 33: 2009-2010; 22: 2010-2011; 18: 2011-2012) UG students in addition to the 5 MEng students, 3 PhD students and one Post-Doc work have worked on different elements to the project.

